

Dynamical DNA: a possible metric of complexity

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"Three Sisters" -- aboriginal womans' place for doing business, near BHPB Yandi iron ore mine

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What do we want in a metric of complexity?

- Direct relationship of metric to dynamical action
- Hierarchical in terms of order of interaction (number of cliques, phrases or scales interacting) and size
- Invariant of coordinates (independent or dependant) and stable to small changes to the dynamics (Lipschitz invariant)
- Direct relationship to group symmetries
- Direct relationship to topological invariants (indexes)



What is wrong with Fourier?

- Invariant of coordinates
- NOT stable to small changes in the dynamics
 - at small scale, small changes in signal lead to large changes in transform

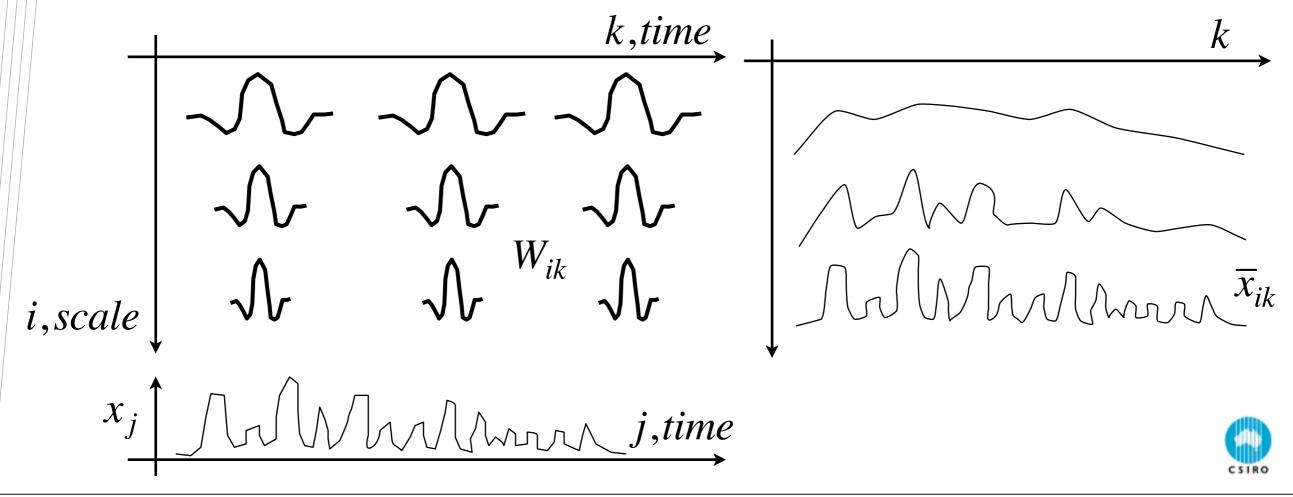


What is wrong with the wavelet transform?

- stable to small changes in the dynamics
- NOT invariant of coordinates

$$\bar{x}_{ik} = \sum_{j} x_{j} W_{ik}(t_{j})$$

where i is the scale and k is the new time index



Interesting development in machine vision

Stephane Mallat's Group Invariant Scattering

- <u>http://arxiv.org/abs/1101.2286</u>
- <u>http://arxiv.org/abs/1011.3023</u>

Define a scattering metric on:

$$d^{2}(f,g) = \|S(f) - S(g)\|^{2} = \sum \|S(p)f - S(p)g\|^{2}$$

where S is a hierarical scattering operation based on iterative wavelet transform

$$S = MWMW \dots = \sum S(p)$$

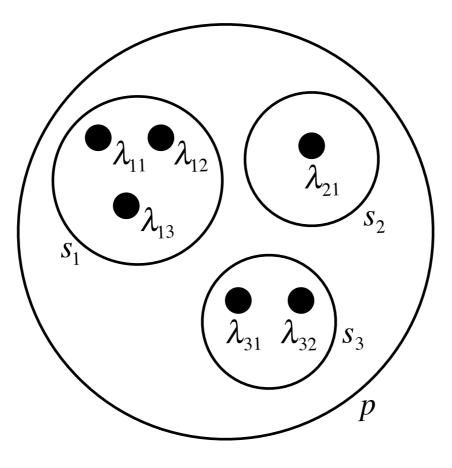
where p is the path in "scale" space

$$S(p)f = |\dots| f * \psi_{s_1} | * \psi_{s_2} | \dots | * \psi_{s_n} | * \psi_{\infty} |$$

In the limit of many MW the transform becomes invariant of independent coordinate (Lie group parameter)



Total path specified by:

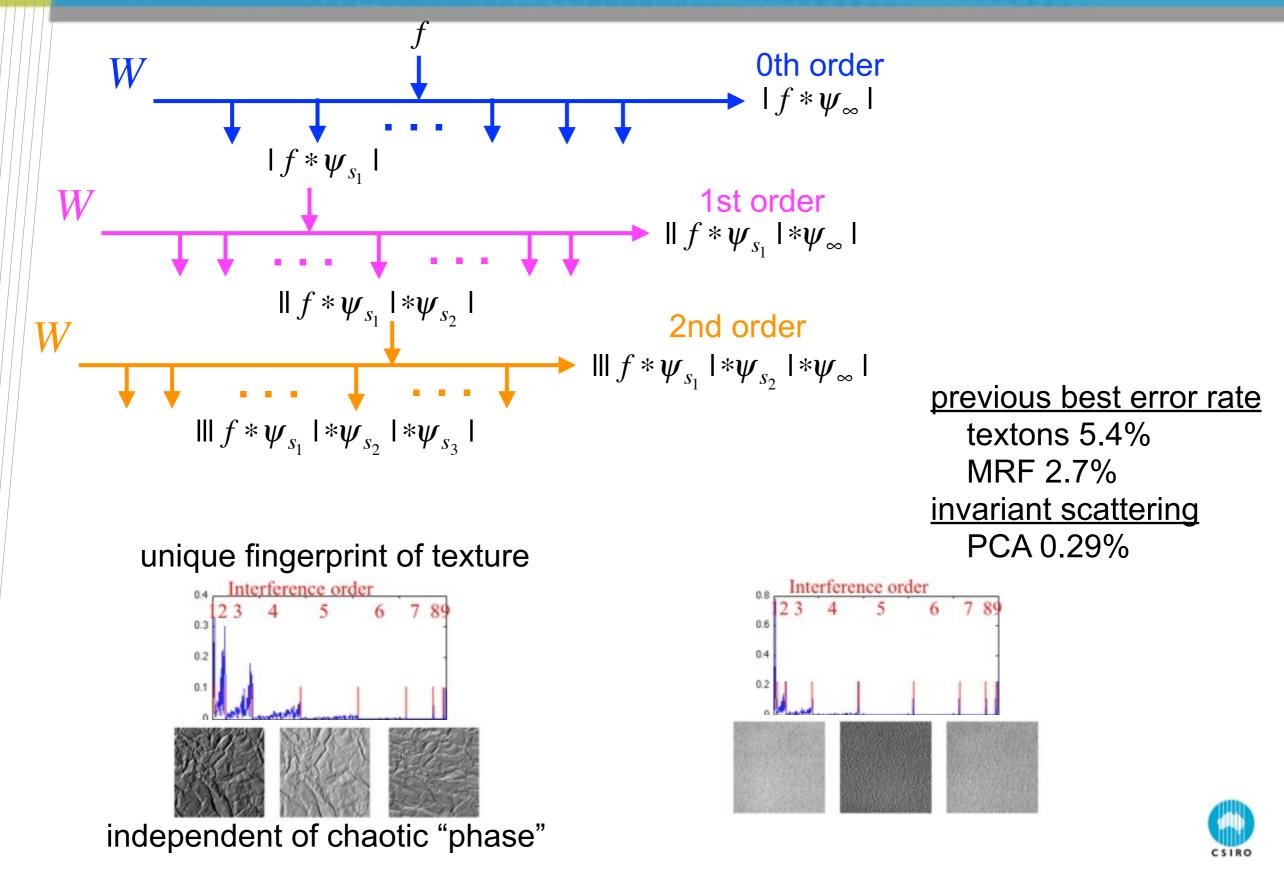


scattering at scale associated with Lie Group translation of independent parameters of deformation field (e.g., k of phonon)

scattering at λ scale associated with GI(n) transformation of dependent parameters (deformation field, e.g., polarization of phonon)



Practical application



What do we have?

- hierarchy
- invariant of coord and stable to small changes in dynamics
- direct relationships to group symmetries (see paper)
- possible relationship to topological index
 - orientation as a function of scale, gives curvatures, gives indexes associated with singularity of system (future R&D)

BUT what does this have to do with complex dynamical systems?



Vision problem can be thought of as dynamics

define the deformation vector field

$$\vec{\tau}(\vec{x}) = [\overleftrightarrow{\tau}(\vec{x}) - [\overleftrightarrow{\tau}(\vec{x_o}) + \overleftarrow{I}] \cdot \vec{\tau}(\vec{x_o})$$

and the associated action

$$S[\vec{x}(t)] = \int_0^{t_o} L(\vec{x}(t), \dot{\vec{x}}(t)) dt$$
$$L(\vec{x}(t), \dot{\vec{x}}(t)) = [\dot{\vec{x}} - \vec{\tau}(\vec{x})] \cdot \vec{g}(\vec{x})$$

image is the wave function

$$f(\vec{x},t) = \int e^{iS[\vec{x}(t)]/\hbar} \mathscr{D}[\vec{x}(t)] f(\vec{x},0)$$

which in the classical image gives the image deformation

$$f(\vec{x},t) = f(\vec{x} - \phi_t(\vec{x})) = f(\vec{x} - \vec{\tau}(\vec{x}))$$



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Mallat's invariant scattering as an interative renormaization

Let us consider a much simpler problem of 1D time dependant dynamics (time sliced)

$$S_o[\{x_j\}] = \sum_j L(x_j, \dot{x}_j, t_j) \Delta t$$

change coordinate to "smoothed" wavelet basis

$$\bar{x}_{ik} = \sum_{i} x_j W_{ik}(t_j)$$

useful mean field approximation in this basis

$$\frac{\partial S_o[\{\bar{x}_{ik}\}]}{\partial \bar{x}_{ik}} = \sum_j W_{ik}(t_j) \frac{\partial L}{\partial x} + W'_{ik}(t_j) \frac{\partial L}{\partial v} \\
= \left\langle \frac{\partial L}{\partial x} \right\rangle_{ik} + \left\langle \frac{d}{dt} \left(\frac{\partial L}{\partial v} \right) \right\rangle_{ik} \\
= \left\langle \nabla L \right\rangle_{ik} + \left\langle \dot{p} \right\rangle_{ik}$$

$$\left\langle \frac{\partial L}{\partial x} \right\rangle_{ik} \equiv \sum_{j} W_{ik}(t_j) \frac{\partial L}{\partial x} \qquad \left\langle \frac{d}{dt} \left(\frac{\partial L}{\partial v} \right) \right\rangle_{ik} \equiv \sum_{j} W_{ik}(t_j) \frac{d}{dt} \left(\frac{\partial L}{\partial v} \right)$$

Renormalization continues and gives the invariant actions, Sp

define the generating function and currents

$$C[\{J_{ik}\}] = ln\left[\int exp\left(-S_o[\{\bar{x}_{ik}\}] + \sum_{ik} J_{ik}\bar{x}_{ik}\right)\prod_{ik} d\bar{x}_{ik}\right]$$

take the Legendre transform to form the effective action

$$S[\{\varphi_{ik}\}] = -C[\{J_{ik}\}] + \sum_{ik} J_{ik}\varphi_{ik}$$

expand the integrand, evaluate by stationary phase, and integrate the the wavelet transformations, one gets the remarkable form for the effective action

$$S[\{\varphi_p\}] = S_o[\{\langle \varphi_p \rangle\}] + \frac{1}{2} \sum_p \frac{\partial^2 S_o[\{\langle \varphi_p \rangle\}]}{\partial \varphi_p^2} \left(\varphi_p - \langle \varphi_p \rangle\right)^2$$

where

$$\left. \frac{\partial S_o}{\partial \varphi_p} \right|_{\langle \varphi_p \rangle} = 0 \qquad \qquad S_p \equiv \frac{1}{2} \left. \frac{\partial^2 S_o}{\partial \varphi_p^2} \right|_{\langle \varphi_p \rangle}$$



S-matrix, stationarity, and restricted ergodicity

look at the definition of the S-matrix and that to leading asymototic order it diagnalizes in the $|\varphi_p\rangle$ basis

$$\hat{S} \equiv \lim_{\substack{t_o o -\infty \ t_f o \infty}} U(x_f, t_f; x_o, t_o) = \lim_{\substack{t_o o -\infty \ t_f o \infty}} \int e^{S_o[\{x_j\}]} \mathscr{D}[\{x_j\}]$$
 $\hat{S} = \lim \int e^{S_o[\{x_j\}]} \mathscr{D}[\{x_j]\} = \lim \int e^{S_{eff}[\{\varphi_p\}]} \mathscr{D}[\{\varphi_p\}]$
 $pprox \lim \int e^{S_o[\langle \varphi_p
angle]} \prod_p exp \left[S_p \left(\varphi_p - \langle \varphi_p
angle
ight)^2\right] d\varphi_p$

now consider the stationary state of the wave function

$$f_{\infty}(x) \equiv f(x,t \to \infty)$$

by a restricted ergodicity on a $|\varphi_p\rangle$ mode basis the wavelet transformation of $f_{\infty}(x)$ with respect to x can be substituted for the wavelet transform of the wave function with respect to t.



Second quantizaiton of the field and metric

$$S = S_o + \sum_p S_p a_p^{\dagger} a_p$$

$$|f\rangle = \prod_p \left(\frac{\left(a_p^{\dagger}\right)^{N_p}}{\left(N_p!\right)^{1/2}}\right) |\varphi_o\rangle, \qquad |\langle\varphi_p|f\rangle|^2 = \frac{N_p}{\sum_p N_p},$$

$$|\varphi_p\rangle = \frac{\left(a_p^{\dagger}\right)^{N_p}}{\left(N_p!\right)^{1/2}} |\varphi_o\rangle, \qquad \langle\varphi_p|S|\varphi_p\rangle = S_o + N_p S_p,$$

$$|\varphi_p\rangle = S_o + \sum_p N_p S_p.$$

projection of $|f\rangle$ onto the $|\varphi_p\rangle$ basis

$$\sum_{p} |\varphi_{p}\rangle \langle \varphi_{p}|f\rangle = MW_{t} \dots MW_{t}f(x(t), t)$$
$$= MW_{x} \dots MW_{x}f_{\infty}(x)$$
$$= Sf_{\infty} = \sum_{p} |\varphi_{p}\rangle S(p)f_{\infty}(x),$$

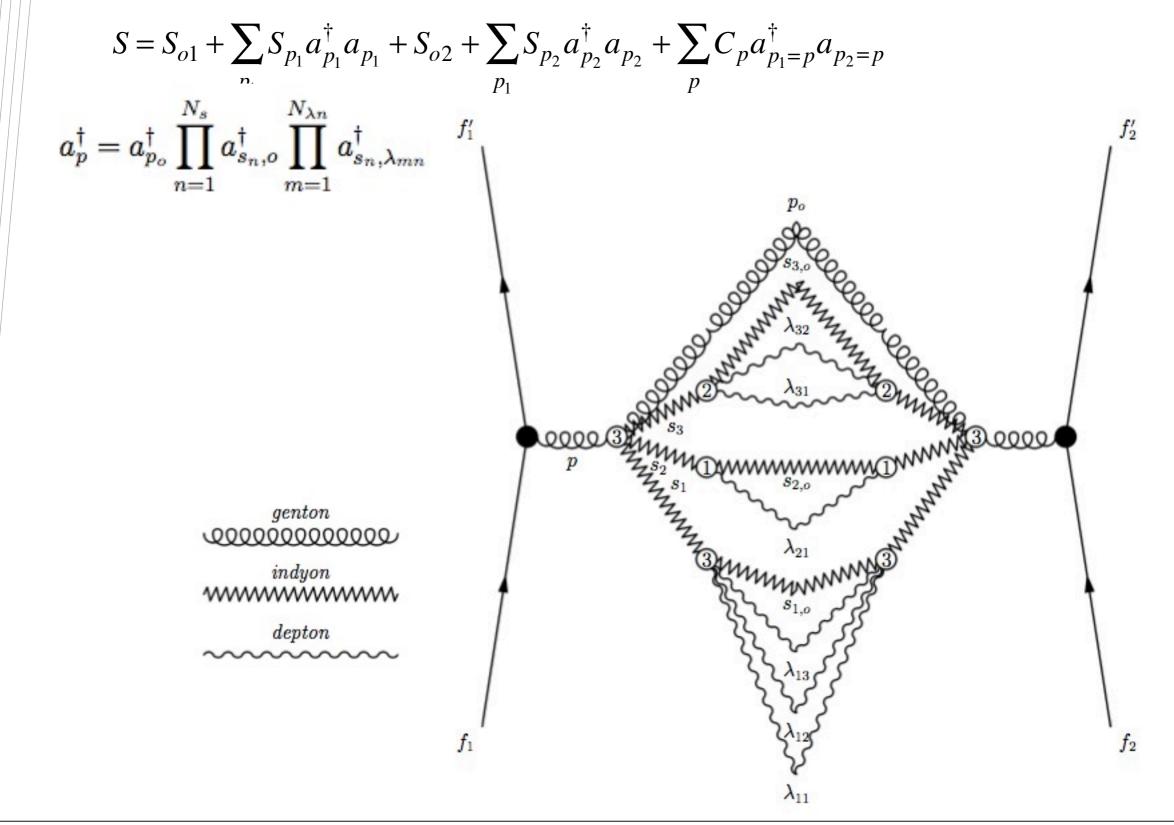
leads to the metric

$$egin{aligned} d^2(f,g) &=& \sum_p |\langle arphi_p | f
angle - \langle arphi_p | g
angle|^2 \ &=& \sum_p |S(p)f - S(p)g|^2 \ &\propto& \sum_p \left(\Delta \sqrt{N_p}
ight)^2, \end{aligned}$$

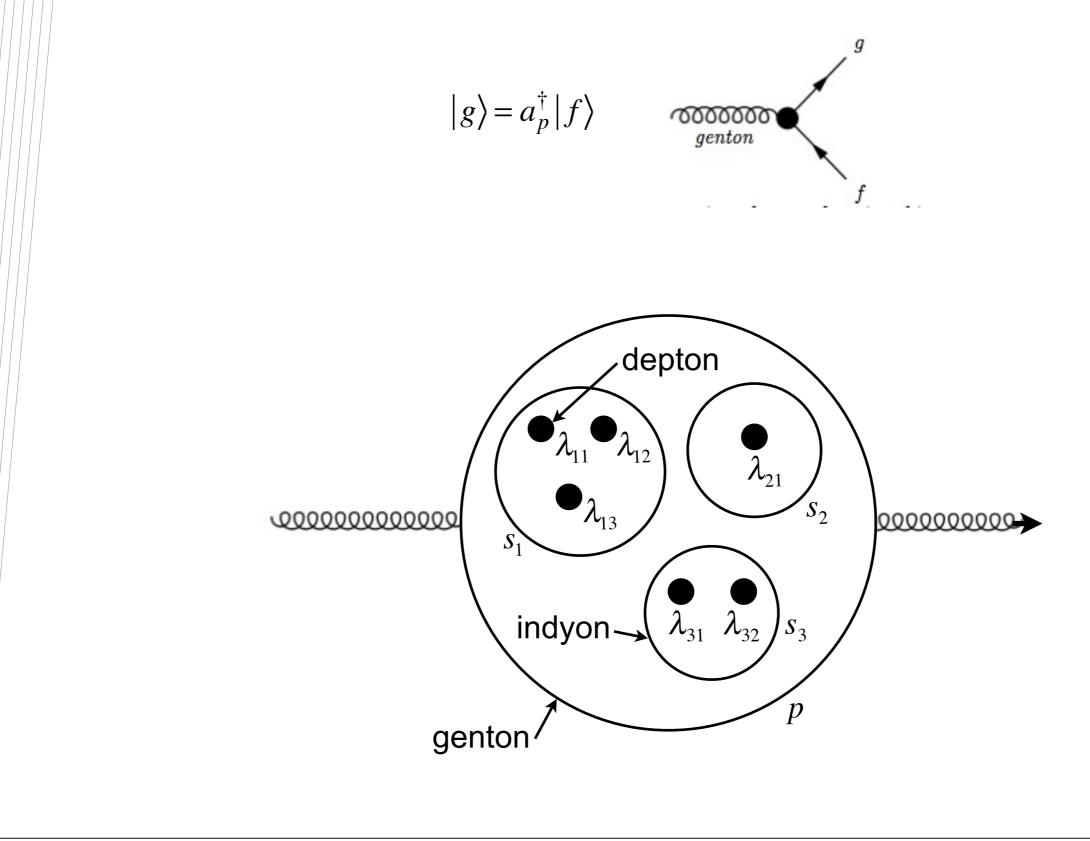
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Feynman diagram of elementary scattering



Revisit of scattering and compact graphical representation



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CSIRO

Conclusions

- Mallat has come up with a transformation (group invariant scattering) that is:
 - very useful in identification of image texture
 - hierarchical
 - invariant to group transformations
 - stable to small changes to the image
- Image identification problem can be formulated as a dynamical system with an action
- Mallat's transformation is an iterative wavelet based renormalization of the dynamics
- the renormalized coordinates are a useful basis leading to:
 - identification of fundamental excitations of system
 - second quantisation of system
 - view of changes in the system as a scattering of the fundamental excitations
 - graphical representation of the scattering in Feynman diagrams
 - definition of metric for the states of the system



Dynamical DNA

- the invariant actions, Sp, fully characterize the dynamics
- they provide a natural basis and metric
- the set of actions are, in analogy to biology, the DNA of the dynamics
 - a coded sequence of numbers, Sp, from which the character of the dynamics can be reconstructed
 - occupation numbers, Np, fully characterize the state of the system